The Minimal Element Theorem

The CMC Dynamics Theorem deals with describing all of the periodic or repeated geometric behavior of a properly embedded CMC surface with bounded second fundamental form in R³ in order to better understand general properties that hold for all such surfaces. Today I will be

discussing my joint work with

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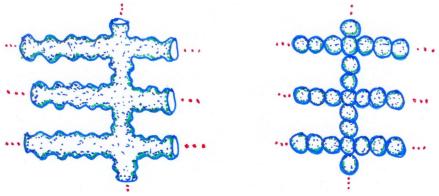
at the University of Notre Dame, South Bend, Indiana, concerning the CMC Dynamics

Theorem with a focus on the CMC Minimal Element Theorem.

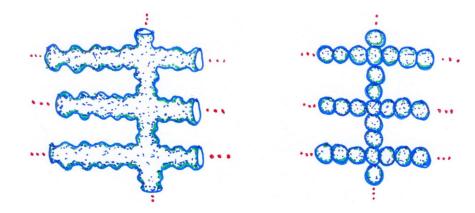
The space T(M) of translational limits of M

Notation

- M ⊂ R³ is a properly embedded CMC surface with bounded second fundamental form.
- W_M is the closed connected component in R³ on the mean convex side of M.
- L(M) is the set of all properly immersed (not necessarily connected) surfaces $\Sigma \subset \mathbb{R}^3$ which are limits of some sequence of translates $M p_n$, where $p_n \in M$ with $|p_n| \to \infty$.
- **T**(**M**) is the set of (pointed) components of surfaces in **L**(**M**) passing through the origin.



- On the left is the singly-periodic surface M, which is the CMC desingularization of the collection of singly-periodic spheres on the right.
- Elements of L(M) are all translates of M and a doubly periodic family of Delaunay surfaces which contain $\vec{0}$.
- Elements of T(M) are translates of M passing through $\vec{0}$ and translates of a fixed Delaunay surface D passing through $\vec{0}$.



The only nonempty **minimal T**-invariant $\Delta \subset T(M)$ is T(D), where $D \in T(M)$ is a fixed Delaunay surface.

Characterization of minimal T-invariant sets

Lemma

A nonempty set $\Delta \subset T(M)$ is a minimal

T-invariant set if and only if whenever

 $\Sigma \in \Delta$, then $T(\Sigma) = \Delta$.

Theorem (CMC Dynamics Theorem in homogeneous manifolds)

Let M denote a noncompact, properly embedded, separating CMC hypersurface with bounded second fundamental form in a homogeneous manifold N. Fix a base point $p \in N$ and a transitive group G of isometries. Let $T_G(M)$ the set of connected, properly immersed submanifolds passing through p which are limits of a divergent sequence of compact domains on M "translated" by elements in G. Then:

- M has a fixed size regular neighborhood on its mean convex side.
- For each $\Sigma \in \mathsf{T}_{\mathsf{G}}(\mathsf{M}) \bigcup \{\mathsf{M}\}$, we have $\mathsf{T}_{\mathsf{G}}(\Sigma) \neq \emptyset$ and $\mathsf{T}_{\mathsf{G}}(\Sigma) \subset \mathsf{T}_{\mathsf{G}}(\mathsf{M})$.
- \bullet $T_G(M)$ and has a natural compact topological space structure induced by a metric.
- Every nonempty T_G -invariant subset of $T_G(M)$ contains a nonempty minimal T_G -invariant subset.

Key properties of minimal elements

Theorem (Minimal Element Theorem)

Suppose that M has possibly nonempty compact boundary and $\Sigma \in T(M)$ is a minimal element. Then:

- $\mathsf{T}(\Sigma) = \mathsf{L}(\Sigma)$, i.e., every surface in $\mathsf{L}(\Sigma)$ is connected.
- If Σ has at least 2 ends, then Σ is a Delaunay surface.
- Σ is chord-arc, i.e., there exists a c>0 such that for $p,q\in\Sigma$ with $d_{R^3}(p,q)\geq 1$, then

$$d_{\Sigma}(p,q) \leq c \cdot d_{\mathbb{R}^3}(p,q).$$

• For all \mathbf{c} , $\mathbf{D} > 0$, there exists a $\mathbf{d}_{c,D} > 0$ such that: For every compact set $\mathbf{X} \subset \mathbf{\Sigma}$ with extrinsic diameter less than \mathbf{D} and for each $\mathbf{q} \in \mathbf{\Sigma}$, there exists a smooth compact, domain $\mathbf{X}_{\mathbf{q},c} \subset \mathbf{\Sigma}$ and a vector, $\mathbf{v}[\mathbf{q},\mathbf{c},\mathbf{D}] \in \mathbf{R}^3$, so that

$$d_{\boldsymbol{\Sigma}}(\boldsymbol{q},\boldsymbol{X}_{\boldsymbol{q},c}) < d_{c,D} \quad \textit{and} \quad d_{\mathcal{H}}(\boldsymbol{X} \;,\; \boldsymbol{X}_{\boldsymbol{q},c} + \boldsymbol{v}[\boldsymbol{q},c,D]) < c.$$

The Alexandrov reflection principle at infinity

Theorem (Halfspace Theorem, R-R, M-T)

If $\mathbf{M} \subset \{\mathbf{x_3} > 0\}$, then $\mathbf{T}(\mathbf{M})$ has a minimal element with the $(\mathbf{x_1}, \mathbf{x_2})$ -plane \mathbf{P} as a plane of Alexandrov symmetry.

Idea of the proof.

Using the fixed sized regular neighborhood of M and the Alexandrov reflection principle, one finds a positive number C so that $M \cap \{x_3 < C\}$ is a graph a smooth function on some domain in P and points $p_n \in M \cap \{x_3 = C\}$ such that the tangent spaces to M at the points p_n converge to the vertical. A subsequence of the translated surfaces $M - p_n$ gives rise to a limit surface $\Sigma \in T(M)$ with the plane P as a plane of Alexandrov symmetry. By the Dynamics Theorem, $T(\Sigma)$ contains the desired minimal element.

M with an infinite number of ends

Lemma (Large Balls Lemma)

If $\mathbb{R}^3 - \mathbb{M}$ contains balls of arbitrarily large radius, then $\mathbb{T}(\mathbb{M})$ has a minimal element with a plane of Alexandrov symmetry.

Proof.

Find a sequence B_n of such open balls so that there exist a divergent sequence of points $p_n \in M \cap \partial B_n$ and a related limit $\Sigma \in T(M)$ arising from $M-p_n$, which lies in the halfspace $\lim_{n \to \infty} (B_n-p_n) \subset R^3$. Then apply the Halfspace Theorem to Σ .

Corollary

If T(M) does not contain a minimal element with a plane of Alexandrov symmetry, then there is an integer K such that the number of ends of M or of any $\Sigma \in L(M)$ is at most K.

Idea of the proof of the corollary.

Suppose that T(M) contains no minimal examples with a plane of Alexandrov symmetry. The proof uses the following fact, for any R>0. Suppose E_1,E_2,\ldots,E_k are disjoint end representatives for a surface $\Sigma\in T(M)$ with boundaries in some ball $\mathbb{B}(R-1)$. When k is sufficiently large, then for every ball B of radius R in $R^3-(\Sigma\cup\mathbb{B}(R))$, B is disjoint from one of these end representatives. Otherwise, one contradicts the uniform cubical volume estimate for all surfaces in T(M) in balls of radius R.

The proof of Large Balls Lemma now works.

M with a plane of Alexandrov symmetry

Theorem (Annular End Theorem)

Suppose M has a plane of Alexandrov symmetry and at least n>1 ends. Then M has at least n annular ends.

Corollary

If $\Sigma \in \mathsf{T}(\mathsf{M})$ is a minimal element, then each surface in $\mathsf{L}(\Sigma)$ has at most one end or else Σ is a Delaunay surface.

Proof of the corollary.

If a surface in $T(\Sigma)$ has a plane of Alexandrov symmetry, then so does Σ and every surface in $L(\Sigma)$, and the corollary follows from the theorem. So assume that no surface in $T(\Sigma)$ has a plane of Alexandrov symmetry. If some surface $\Sigma' \in L(\Sigma)$ has n>1 ends, then the Large Balls Lemma implies every surface in $L(\Sigma')$ has at least n components. Choose $F \in L(\Sigma')$ with Σ as a component. Repeating this argument, $L(F) \subset L(\Sigma')$ has an element with 2n-1 ends. So $T(\Sigma)$ has an element with a plane of Alexandrov symmetry, a contradiction.

Minimal elements $\Sigma \in T(M)$ are chord-arc

Theorem

Minimal elements $\Sigma \in T(M)$ are chord-arc.

Proof: For $p, q \in \mathbb{R}^3$, $\mathbf{d}(p, q) = \mathbf{d}_{\mathbb{R}^3}(p, q)$. Let $\Sigma \in \mathsf{T}(\mathsf{M})$ be a minimal element.

Assertion

There exists a function $\mathbf{f}: [1, \infty) \to [1, \infty)$ so that for $p, q \in \Sigma$ with $1 \leq \mathbf{d}(p, q) \leq R$, $\mathbf{d}_{\Sigma}(p, q) \leq \mathbf{f}(R) \cdot \mathbf{d}(p, q)$.

Proof.

Otherwise there exists an R_0 and points $p_n, q_n \in \Sigma$ with $\mathbf{d}(p_n, q_n) \leq R_0$ and $n \leq \mathbf{d}_{\Sigma}(p_n, q_n)$. Then $(\Sigma - p_n) \longrightarrow \Sigma_{\infty} \in \mathbf{L}(\Sigma)$ which is disconnected; this contradicts previous corollary, so \mathbf{f} exists.



Minimal elements $\Sigma \in T(M)$ are chord-arc

- There exists a function $\mathbf{f} \colon [1,\infty) \to [1,\infty)$ so that for $p,q \in \Sigma$ with $1 \leq \mathbf{d}(p,q) \leq R$, $\mathbf{d}_{\Sigma}(p,q) \leq \mathbf{f}(R) \cdot \mathbf{d}(p,q)$.
- Case A: Every ball of a fixed radius R 1 in R³ intersects Σ.

Let $p,q\in \Sigma$ such that $\mathbf{d}(p,q)\geq 4\mathbf{R}$. Let B_1,\ldots,B_n be a chain of closed balls of radius \mathbf{R} centered along the line segment joining p,q and with points $s_i\in B_i\cap \Sigma$ and $s_1=p,s_n=q$, and so that, $1\leq \mathbf{d}(s_i,s_{i+1})\leq 4\mathbf{R}$. Note $(n-1)2\mathbf{R}\leq \mathbf{d}(p,q)$.

Minimal elements $\Sigma \in T(M)$ are chord-arc

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- Case A: Every ball of a fixed radius R − 1 in R³ intersects ∑.

Proof.

Let $p,q\in \Sigma$ such that $\mathbf{d}(p,q)\geq 4\mathbf{R}$. Let B_1,\ldots,B_n be a chain of closed balls of radius \mathbf{R} centered along the line segment joining p,q and with points $s_i\in B_i\cap \Sigma$ and $s_1=p,s_n=q$, and so that, $1\leq \mathbf{d}(s_i,s_{i+1})\leq 4\mathbf{R}$. Note $(n-1)2\mathbf{R}\leq \mathbf{d}(p,q)$. By the triangle inequality,

$$\mathbf{d}_{\Sigma}(p,q) \leq \sum_{i=1}^{n-1} \mathbf{d}_{\Sigma}(s_i,s_{i+1}) \leq \sum_{i=1}^{n-1} \mathbf{f}(4\mathsf{R})\mathbf{d}(s_i,s_{i+1})$$

$$\leq \mathbf{f}(4\mathsf{R}) \cdot (n-1)4\mathsf{R} \leq 2\mathbf{f}(4\mathsf{R}) \cdot \mathbf{d}(p,q).$$

Case B: Σ has a plane of Alexandrov symmetry. The proof of this case uses similar arguments as in Case A. This completes the proof of the chord-arc property of minimal elements.

Theorem (Annular End Theorem)

Suppose M has a plane of Alexandrov symmetry and at least n>1 ends. Then M has at least n annular ends. In particular, n has a finite number of ends greater than n if and only if it has finite topology.

Proof: Suppose M is a bigraph over a domain Δ in the x_1x_2 -plane and M_1 , $M_2 \subset M$ are ends of M, which are components in the complement of a vertical cylinder of radius R_0 . Suppose M_i is a bigraph over $\Delta_i \subset \Delta$.

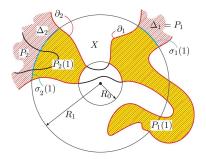


Figure: $\sigma_1(1)$ is the short arc in the circle of radius R_1 . $P_1(1)$ is the yellow shaded region containing $\sigma_1(1)$ and an arc of ∂_1 in its boundary. By the Alexandrov reflection principle and height estimates for *CMC* graphs, P_1 lies 1/H close to any vertical halfspace containing $\sigma_1(1)$.

After a horizontal translation and a rotation of \mathbf{M}_1 around the x_3 -axis, we may assume that \mathbf{M}_1 lies in $\{(x_1,x_2,x_3) \mid x_2>0\}$. The proof of the Halfspace Theorem shows that after another rotation, we may also assume Δ_1 also contains divergent sequence of points $p_n=(x_1(n),x_2(n),0)\in\partial\Delta_1$ such that $\frac{x_2(n)}{x_1(n)}\to 0$ as $n\to\infty$ and the surfaces \mathbf{M}_1-p_n converge to a Delaunay surface.

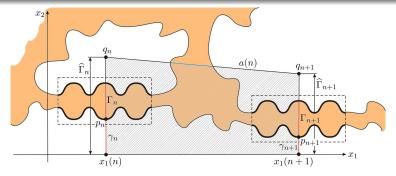


Figure: Choosing the points $p_n \in M_1$ and related data.

Our goal is to show M_1 contains an annular end. This follows from the next assertion.

Assertion

The regions between forming Delaunay surfaces near p_n are annuli.

The assertion holds if the segment $a(n) \cap \Delta_1$ bounds a compact domain in (above) Δ_1 .

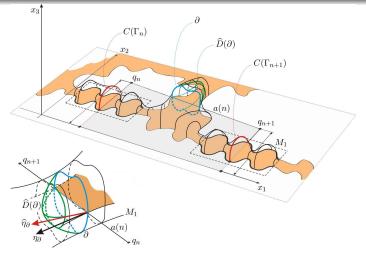


Figure: Blowing a green bubble $\widehat{D}(\partial)$ on the mean convex side of \mathbf{M}_1 . Existence of **green** bubble implies that for some $\mathbf{c}>0$, the *CMC* flux \mathbf{F} of $E_2=\nabla x_2$ on the portion X_n of \mathbf{M}_1 over the shaded rectangle satisfies $\mathbf{F}>\mathbf{c}$, contradicting a standard application of the divergence theorem.

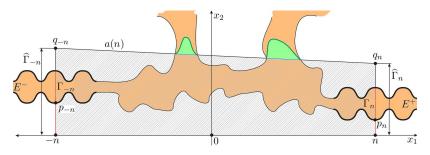


Figure: A picture of M_1 with two bubbles blown on its mean convex side.