Solve five of the following six problems. Show all your work and justify all your answers.

1. (22 points) Set $A:=\left(\begin{array}{ccc}1 & 2 & 0 \\ 0 & 1 & 2 \\ 2 & 0 & 1\end{array}\right)$.
(a) Show that the characteristic polynomial of $A$ is equal to $(x-3)\left(x^{2}+3\right)$. Show your work!
(b) Find a basis of $\mathbb{C}^{3}$ consisting of eigenvectors of $A$. Hint: Use the notation $\eta=\frac{-1+\sqrt{3} i}{2}$, $\bar{\eta}=\frac{-1-\sqrt{3} i}{2}$ and note that $\eta \bar{\eta}=1$ and $\eta^{3}=1$ (so $\bar{\eta}=\eta^{2}$ ).
(c) Find an invertible matrix $P$ and a diagonal matrix $D$, both in $M_{3}(\mathbb{C})$, such that $P^{-1} A P=$ $D$.
2. (22 points) Let $A=\left(\begin{array}{ccc}2 & 3 & 1 \\ 0 & -1 & 0 \\ -1 & -1 & 0\end{array}\right)$ and work over the field $\mathbb{R}$ of real numbers.
(a) Show that the characteristic polynomial of $A$ is $(x+1)(x-1)^{2}$.
(b) Find a basis for each eigenspace of $A$.
(c) Check that each vector you found in part 2 b is indeed an eigenvector!
(d) Find the minimal polynomial of $A$. Justify your answer!
(e) Find a basis for each $V_{i}$ in the Primary Decomposition $\mathbb{R}^{3}=V_{1} \oplus V_{2}$ with respect to $A$.
(f) Find the elementary divisors of $A$. Carefully justify your answer!
(g) Find the Jordan canonical form of $A$. Justify your answer!
(h) Find an invertible matrix $P$, such that $P^{-1} A P$ is in the Jordan canonical form you provided in part 2 g . Describe your method in complete sentences! Credit will not be given to a solution found by trial and error.
3. (22 points)
(a) The matrix $A=\left(\begin{array}{cc}3 & 1 \\ -1 & 1\end{array}\right)$ satisfies $P^{-1} A P=\left(\begin{array}{ll}2 & 1 \\ 0 & 2\end{array}\right)$, where $P=\left(\begin{array}{cc}1 & 0 \\ -1 & 1\end{array}\right)$. Use this information to obtain formulas for the entries of the matrix $e^{t A}$ as functions of $t$. State (in words) each algebraic property, of the exponential of a matrix, you use.
(b) Use your work in part 3a to show that the solution $\left(y_{1}(t), y_{2}(t)\right)$ of the system

$$
\begin{aligned}
& \frac{\partial y_{1}}{\partial t}=3 y_{1}+y_{2} \\
& \frac{\partial y_{2}}{\partial t}=-y_{1}+y_{2}
\end{aligned}
$$

satisfying $y_{1}(0)=a$ and $y_{2}(0)=b$ is

$$
\begin{aligned}
y_{1}(t) & =a e^{2 t}+(a+b) t e^{2 t} \\
y_{2}(t) & =b e^{2 t}-(a+b) t e^{2 t} .
\end{aligned}
$$

4. (22 points) Let $A=\left(\begin{array}{cccc}2 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 2\end{array}\right)$ and $B=\left(\begin{array}{llll}2 & 0 & 0 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 2\end{array}\right)$.
(a) Let $T: \mathbb{R}^{4} \rightarrow \mathbb{R}^{4}$ be the linear transformation given by $T(v)=A v$. How many direct summands appear in the Primary Decomposition of $\mathbb{R}^{4}$ with respect to $T$ ? Justify your answer!
(b) Show that for every vector $v$ in $\mathbb{R}^{4}$, the order $m_{v}(x)$ of $v$ with respect to $T$ is a power of $(x-2)$.
(c) Find the orders $m_{e_{1}}(x), m_{e_{2}}(x), m_{e_{3}}(x), m_{e_{4}}(x)$ with respect to $T$, for the elements of the standard basis of $\mathbb{R}^{4}$. Hint: You may want to use the following equality (you do not need to prove it) $\operatorname{span}\left\{v, A v, A^{2} v, \ldots\right\}=\operatorname{span}\left\{v,(A-2 I) v,(A-2 I)^{2} v, \ldots\right\}$.
(d) Use your work in part 4 c in order to find a decomposition of $\mathbb{R}^{4}$ as a direct $\operatorname{sum}\left\langle v_{1}\right\rangle \oplus$ $\left\langle v_{2}\right\rangle \oplus \cdots \oplus\left\langle v_{k}\right\rangle$ of cyclic subspaces with respect to $T$, such that $m_{v_{i}}(x)$ is a power of a prime polynomial in $\mathbb{R}[x]$. Justify your answer!
(e) Are the matrices $A$ and $B$ similar? Use your work above to justify your answer. $B$ is given at the beginning of Question 4.
5. (22 points)
(a) Let $A$ be an $n \times n$ matrix with real entries and $T: \mathbb{C}^{n} \rightarrow \mathbb{C}^{n}$ the linear transformation given by multiplication by $A$. Assume that $\lambda=a+b i$ is an eigenvalue of $T$. Show that the complex conjugate $\bar{\lambda}=a-b i$ is an eigenvalue of $T$ as well.
(b) Let $V$ be an inner product space (over $\mathbb{R}$ ) and $T: V \rightarrow V$ an orthogonal transformation. Show that if $\lambda$ is an eigenvalue of $T$, then $\lambda=1$ or $\lambda=-1$.
(c) Assume that in part 5 b the dimension of $V$ is odd. Show that $T$ has an eigenvector with eigenvalue 1 or -1 . Hint: Use part 5 a.
(d) Consider $\mathbb{R}^{3}$ as an inner product space with respect to the dot product and let $T: \mathbb{R}^{3} \rightarrow \mathbb{R}^{3}$ be an orthogonal transformation. Assume that $u$ is an eigenvector of $T$ and let $W$ be the plane orthogonal to $u$. Show that $W$ is $T$-invariant (i.e., that $T(w)$ belongs $W$, for all $w$ in $W)$.
(e) Keep the notation of part 5d. Show that the restriction $T_{W}: W \rightarrow W$ of $T$ to $W$ is an orthogonal transformation.
(f) Keep the notation of part 5d. Assume, in addition, that the eigenvalue of $u$ is 1 and that $\operatorname{det}(T)=1$. Show that there exists a basis $\beta_{2}:=\{v, w\}$ of $W$, such that the matrix of $T$ with respect to the basis $\beta:=\{u, v, w\}$ is of the form $\left(\begin{array}{ccc}1 & 0 & 0 \\ 0 & \cos (\theta) & -\sin (\theta) \\ 0 & \sin (\theta) & \cos (\theta)\end{array}\right)$, for some angle $\theta$. Hint: You may use the fact that a $2 \times 2$ orthogonal matrix with determinant 1 is the matrix of a rotation of $\mathbb{R}^{2}$.
6. (22 points)
(a) Recall that a linear transformation $E: V \rightarrow V$ is eidempotent, if $E$ is non-zero, and $E^{2}=E$. Show that every eidempotent linear transformation is diagonalizable.
(b) Let $T: \mathbb{R}^{3} \rightarrow \mathbb{R}^{3}$ be a linear transformation with standard matrix $A$ and minimal polynomial $m(x)=(x-2)^{2}(x-3)$. Set $q_{1}(x)=(x-3)$ and $q_{2}(x)=(x-2)^{2}$. Find a polynomial $a_{1}(x)=$ $a x+b$ of degree 1 and a constant polynomial $a_{2}(x)=c$, such that $a_{1}(x) q_{1}(x)+a_{2}(x) q_{2}(x)=1$ (the constant polynomial 1).
(c) Set $E_{1}:=a_{1}(A) q_{1}(A)$ and $E_{2}:=a_{2}(A) q_{2}(A)$. Show that $E_{1} E_{2}=E_{2} E_{1}, E_{1}+E_{2}=I$, where $I$ is the identity matrix.
(d) Keep the notation of part 6c. Show that $E_{1} E_{2}=0$.
(e) Keep the notation of part 6c. Show that $E_{1}$ and $E_{2}$ are idempotent matrices.
(f) Let $A=\left(\begin{array}{ccc}1 & 0 & 1 \\ 1 & 3 & -1 \\ -1 & 0 & 3\end{array}\right)$. The minimal polynomial of $A$ is $m(x)=(x-2)^{2}(x-3)$. You are not asked to prove it. Calculate the matrices $E_{1}$ and $E_{2}$ for this matrix $A$. Hint: Start with $E_{2}$ to save calculations.
