- 1. (4 points) Let A be a  $5 \times 11$  matrix (5 rows and 11 columns). Denote the rank of A by r.
  - (a) The rank of A must be in the range  $\underline{\phantom{a}} \leq r \leq \underline{\phantom{a}}$ .
  - (b) Express the dimension of the null space of A in terms of r. dim  $\text{Null}(A) = \underline{\hspace{1cm}}$ .
  - (c) Express the dimension of the column space of A in terms of r. dim  $Col(A) = \underline{\hspace{1cm}}$ .
  - (d) Express the dimension of the row space of A in terms of r. dim  $Row(A) = \underline{\hspace{1cm}}$ .
- 2. (6 points) Let W be the plane in  $\mathbb{R}^3$  spanned by  $u_1 = \begin{pmatrix} 2 \\ -1 \\ -4 \end{pmatrix}$  and  $u_2 = \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix}$ 
  - (a) Find the projection of  $b = \begin{pmatrix} 4 \\ 1 \\ 0 \end{pmatrix}$  to W.
  - (b) Find the distance from b to W.
- 3. (18 points) The matrices A and B below are row equivalent (you do **not** need to check this fact).

$$A = \begin{pmatrix} 1 & 1 & 1 & 2 & 7 & 8 \\ 2 & 1 & 3 & 3 & 0 & 0 \\ 3 & 2 & 4 & 5 & 1 & 4 \\ 0 & 0 & 0 & 0 & 3 & 2 \\ 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix} \qquad B = \begin{pmatrix} 1 & 0 & 2 & 1 & 0 & 0 \\ 0 & 1 & -1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

- a) What is the rank of A?
- b) Find a basis for the null space Null(A) of A.
- c) Find a basis for the column space of A.
- d) Find a basis for the row space of A.
- 4. (18 points) Let W be the line in  $\mathbb{R}^3$  spanned by  $w = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$ .
  - (a) Find the length of  $v = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$ .
  - (b) Find the projection of v to the line W.
  - (c) Find the distance between v and the line W.
  - (d) Denote by  $W^{\perp}$  the plane (through  $\vec{0}$ ), which is orthogonal to w. Write v as a sum of a vector in W and a vector in  $W^{\perp}$ .
  - (e) Find the distance from v to  $W^{\perp}$ .
  - (f) Find an orthogonal basis  $\{u_1, u_2\}$  for  $W^{\perp}$ . Hint: Let  $u_1$  be the vector in  $W^{\perp}$  you found in part 4d. Now find  $u_2$  orthogonal to both w and  $u_1$ .
- 5. (18 points)

- (a) Show that the characteristic polynomial of the matrix  $A = \begin{pmatrix} 2 & 1 & -1 \\ 1 & -1 & -1 \\ 0 & 1 & 1 \end{pmatrix}$  is  $-(\lambda 1)(\lambda + 1)(\lambda 2)$ .
- (b) Find a basis of  $\mathbb{R}^3$  consisting of eigenvectors of A.
- (c) Find an invertible matrix P and a diagonal matrix D such that the matrix A above satisfies

$$P^{-1}AP = D$$

- 6. (18 points) The vectors  $v_1 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$  and  $v_2 = \begin{pmatrix} 3/7 \\ 4/7 \end{pmatrix}$  are eigenvectors of the matrix  $A = \begin{pmatrix} .6 & .3 \\ .4 & .7 \end{pmatrix}$ .
  - (a) The eigenvalue of  $v_1$  is \_\_\_\_\_

The eigenvalue of  $v_2$  is \_\_\_\_\_

- (b) Find the coordinates of  $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$  in the basis  $\{v_1, v_2\}$ .
- (c) Compute  $A^{100} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ .
- (d) As n gets larger, the vector  $A^n\begin{pmatrix} 1\\1 \end{pmatrix}$  approaches \_\_\_\_. Justify your answer.

## 7. (18 points)

- (a) Find the matrix A of the rotation of  $\mathbb{R}^2$  an angle of  $\frac{\pi}{2}$  radians (90°) counter-clockwise.
- (b) Find the matrix B of the reflection of the plane about the line  $x_1 = 0$  (the  $x_2$  coordinate line).
- (c) Compute  $C = A^{-1}BA$ . Is C the matrix of a rotation? (if yes, find the angle). Is C the matrix of a reflection? (if yes, find the line of reflection).
- 8. (18 points) Let *B* be the matrix  $\begin{bmatrix} 4 & -7 & 4 \\ -1 & 4 & 8 \\ -8 & -4 & 1 \end{bmatrix}$  and  $A = \frac{1}{9}B$ .
  - (a) Show that the columns  $\{\vec{a}_1, \vec{a}_2, \vec{a}_3\}$  of A form an orthonormal basis of  $\mathbb{R}^3$ .
  - (b) Use part 8a to find the coordinates of the vector  $\begin{bmatrix} 1\\1\\1 \end{bmatrix}$  in the basis  $\{\vec{a}_1, \vec{a}_2, \vec{a}_3\}$ .
  - (c) A is the matrix of a rotation of  $\mathbb{R}^3$  about a line L through the origin (you may assume this fact). **Explain** why any non-zero vector v in L must be an eigenvector of A and determine its eigenvalue.
  - (d) Find a vector v which spans the axis of rotation of A (the line L in part 8c). Hint: You may avoid calculations with fractions by working with the matrix B. Use the fact that a vector v is an eigenvector of A with eigenvalue  $\lambda$ , if and only if v is an eigenvector of B with eigenvalue  $9\lambda$ .